IN THE CLAIMS:

The following listing of claims replaces all prior versions and listings of claims in the present application.

<u>Listing of Claims</u>:

- 1-19. (Cancelled)
- 20. (Currently Amended) Brake system with two brake circuits for a vehicle, comprising a brake servo assistance unit for automatic generation of brake force, and at least one pressure sensor for generation of a measuring signal representative of an activity on a driver's part and fed to a brake pressure control unit, with an activation control signal for actuation of the brake servo assistance unit being generated in the event measuring signals from the sensors exceed a reference value, wherein

two pressure sensors are provided and have different reference values assigned thereto, each of the pressure sensors being operatively associated with one of the brake circuits (11a; 11b), and the activation control signal is generated for temporary activation of the brake servo assistance unit for a limited time period in the event that a higher of the reference value from the first pressure sensor is exceeded and a lower of the reference values for the second pressure sensor has not yet been attained exceeded, and if conditions for permanent activation are unfulfilled for the limited time period a deactivation control signal is automatically generated.

- 21. (Previously Presented) Brake system according to claim 20, wherein at least one of absolute values and gradients are generated as the measuring signals.
- 22. (Previously Presented) Brake system according to claim 20, wherein one of the reference values is generated by multiplying the first reference value by a reduction factor of less than one.
- 23. (Currently Amended) Brake system according to claim 20, wherein the temporary activation is maintained for a limited, defined number of working cycles of the control unit and thereafter a the deactivation control signal is generated for deactivation of the brake servo assistance unit.
- 24. (Previously Presented) Brake system according to claim 20, wherein the temporary activation is maintained in the event that the measuring signal from a second of the pressure sensors exceeds a reduced reference value during a defined number of working cycles.
- 25. (Currently Amended) Brake system according to claim 20, wherein a the deactivation control signal deactivating the brake servo assistance unit is generated in the event that the measuring signal from one of the sensors falls below a reference value.

- 26. (Previously Presented) Brake system according to claim 20, wherein at least one travel sensor is provided for measuring the activity on the driver's part.
- 27. (Previously Presented) Brake system according to claim 26, wherein an activation control signal is generated in the event that a pressure gradient of one pressure sensor and a speed value calculated from successive measuring signals of the travel sensor each exceed a reference value.
- 28. (Previously Presented) Brake system according to claim 26, wherein an activation control signal is generated in the event that a pressure value of the pressure sensor and a speed value of the travel sensor each exceed a reference value.
- 29. (Previously Presented) Brake system according to claim 26, wherein an activation control signal is generated in the event that a pressure gradient of the pressure sensor and a travel of the travel sensor each exceed a reference value.
- 30. (Currently Amended) Brake system according to claims 26, wherein a the deactivation control signal is generated in the event that the measuring signal from the travel sensor falls below a reference value.
- 31. (Currently Amended) Brake system according to claim 20, wherein a trip switch is provided for deactivation of the brake servo

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assistance unit operatively installed in the brake booster of the brake system, whereby a the deactivation control signal is generated in the event that a measuring signal of the trip switch falls below a reference value.

32. (Previously Presented) Brake system according to claim 20, wherein the measuring signals from the sensors for generating the activation control signal are such as to occur within a defined time window.